

Robotics for Bioengineering (RB)
INDUSTRIAL BIOENGINEERING (LAUREA MAG.)

A.A. 2023/2024

LUN	NA-II-A11 (11h30-13h30)
MER	NA-II-A6 (13h30-15h30)

L1	04/03 - Mon	Introduction to robotics and medical robotics
L2	06/03 - Wed	Pose of rigid body, rotation matrix, composition of rotation matrices
L3	11/03 - Mon	Orientation representations (Euler angles, angle and axis, unit quaternion), homogeneous transformations
L4	13/03 - Wed	Direct kinematics, Denavit-Hartenberg convention, Kinematics of typical manipulator structures
L5	18/03 - Mon	Closed chain, parallelogram arm
L6	20/03 - Wed	Joint space and operational space, Inverse kinematics problem
L7	25/03 - Mon	Differential kinematics, geometric Jacobian, Jacobian of typical manipulator
L8	27/03 - Wed	Kinematic singularities, analysis of redundancy
L9	3/04 - Wed	Use of redundancy, inverse differential kinematics, analytical Jacobian
L10	8/04 - Mon	Seminar
L11	10/04 - Wed	Inverse kinematics algorithms
L12	15/04 - Mon	Comparison among inverse kinematics algorithms, statics, manipulability ellipsoids
L13	17/04 - Wed	Classification of surgical robots
L14	22/04 - Mon	Seminar
L15	24/04 - Wed	da Vinci research kit, kinematics and dynamics
L16	6/05 - Mon	da Vinci research kit: software and control architecture, KUKA & Simulators
L17	8/05 - Wed	Direct dynamics and inverse dynamics, operational space dynamic model, dynamic manipulability ellipsoid
L18	13/05 - Mon	Robotic hands and prosthesis
L19	15/05 - Wed	Postural synergies for design and control
L20	20/05 - Mon	Exoskeletons: design and actuation
L21	22/05 - Wed	Exoskeletons: sensing and control
L22	27/05 - Mon	Centralized control: PD control with gravity compensation, inverse dynamics control
L23	29/05 - Wed	Operational space control: PD control with gravity compensation, inverse dynamics control, comparison among various control scheme
L24	4/06 - Tue	Lab Visit